

# Galileo – Systemaufbau und Mehrwert

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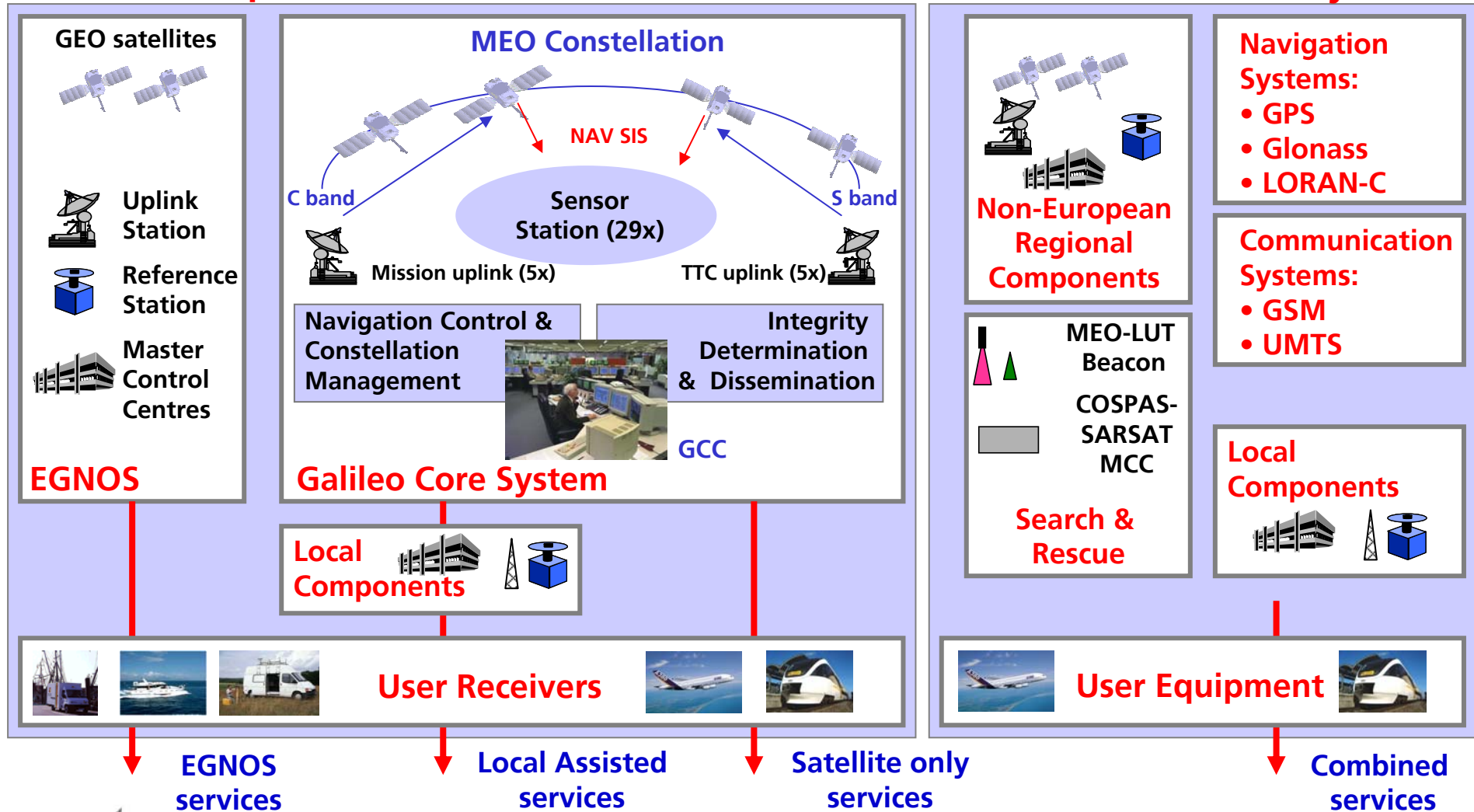
## Topics

- **Galileo – Systemaufbau**
- **Galileo Mehrwert**
  - >> **aus Satellitenverfügbarkeit**
  - >> **aus Signalverfügbarkeit**
  - >> **aus spezifischen Diensten**
  - >> **aus Interoperabilität**
- **Meilenstein: Galileo Testsatellit**
- **Galileo Verwertung**

# Galileo Systemaufbau

## Galileo Komponenten

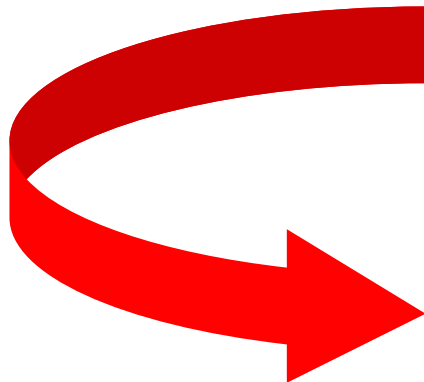
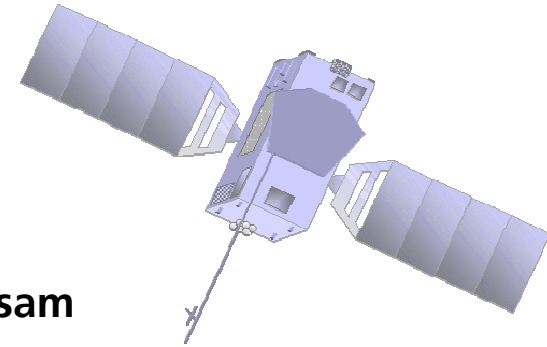
## Externe Systeme





## Technischer Mehrwert - Galileo

- **Unabhängigkeit:** GALILEO ist ein komplettes, eigenständiges GNSS.
- **Verfügbarkeit:** GALILEO ist global verfügbar. Bessere Konstellationsgeometrie.
- **Interoperabilität:** GALILEO + GPS können gemeinsam genutzt werden.
- **Performance:** Services kundenoptimiert, Mehrfrequenzempfang / Ranging Performance.
- **Verantwortlichkeit:** Eigenständige Überwachung der Services und ihrer Performance durch Real Time Integrity Network.

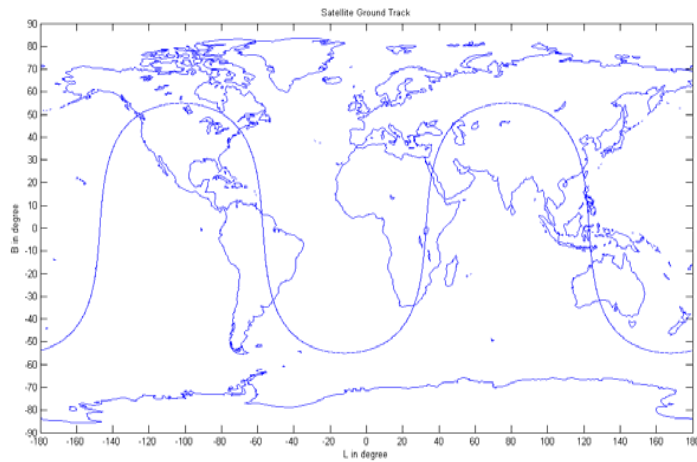
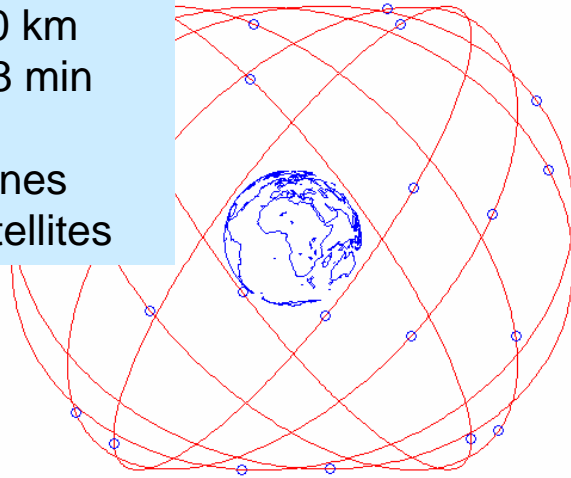


- ✓ Service Garantien werden gegeben
- ✓ Integritätsinformationen werden geliefert
- ✓ SoL Zertifizierung wird möglich
- ✓ Lokale Ergänzungen bereits im Design berücksichtigt
- ✓ Kompatibilität zu GPS unterstützt die Nutzung beider ( Redundanz, Verfügbarkeit)



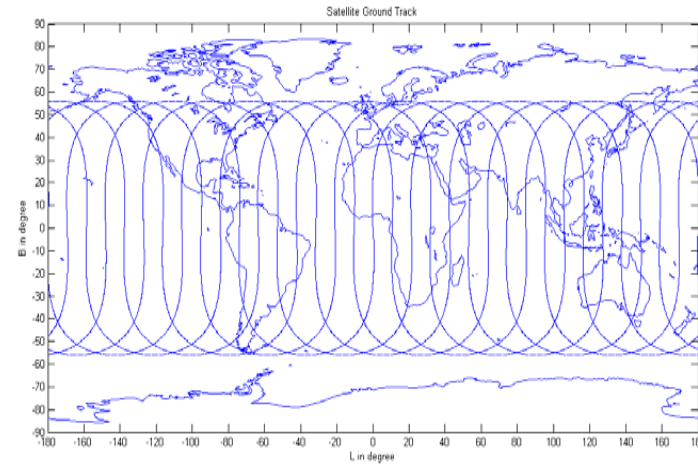
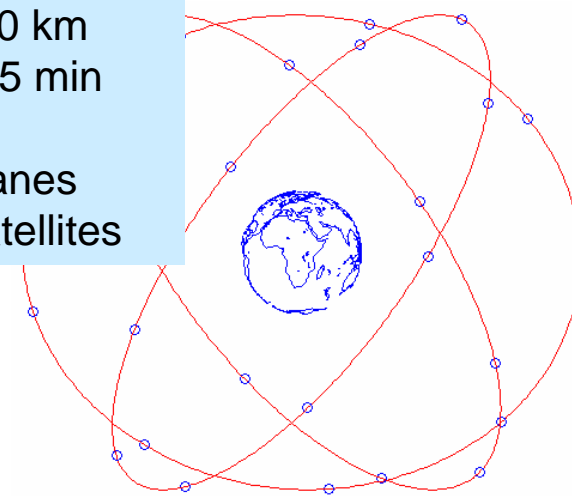
## GPS

R = 26'600 km  
T = 11h 58 min  
i=55°,  
6 orbit planes  
24 (28) satellites



## Galileo

R = 29'600 km  
T = 14h 05 min  
i=56°,  
3 orbit planes  
27 (30) satellites



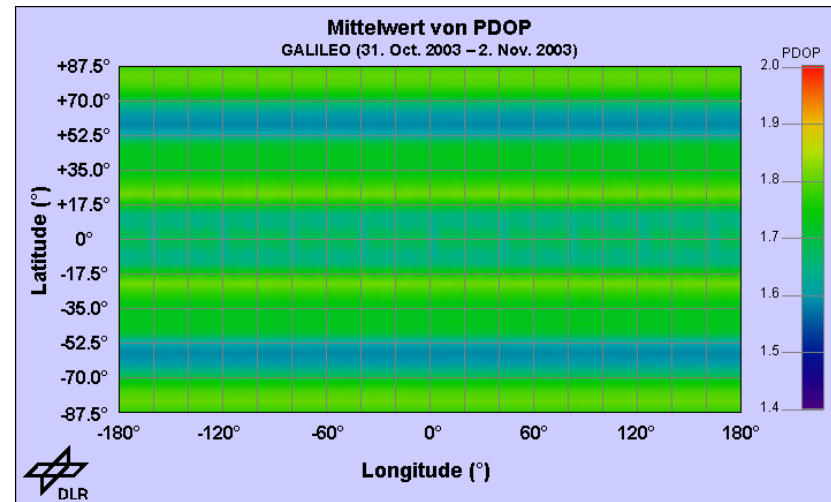
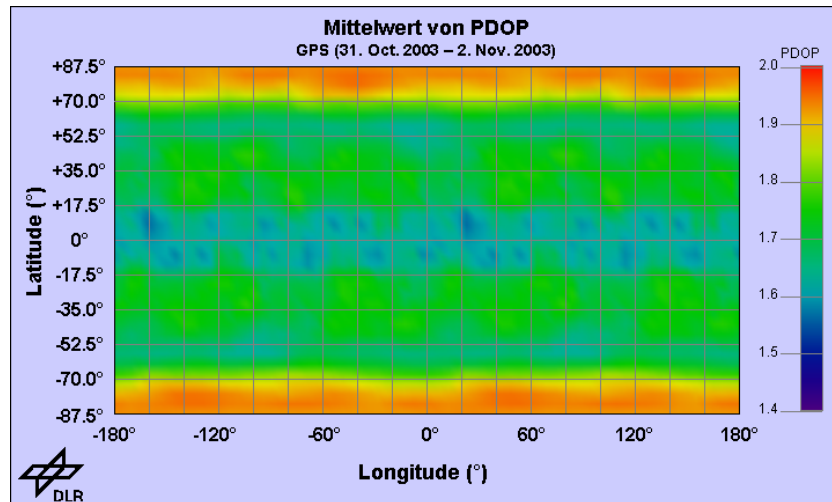
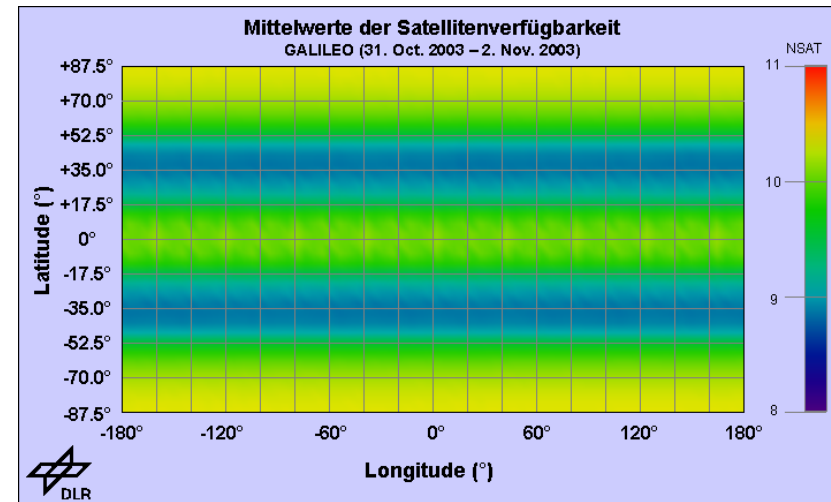
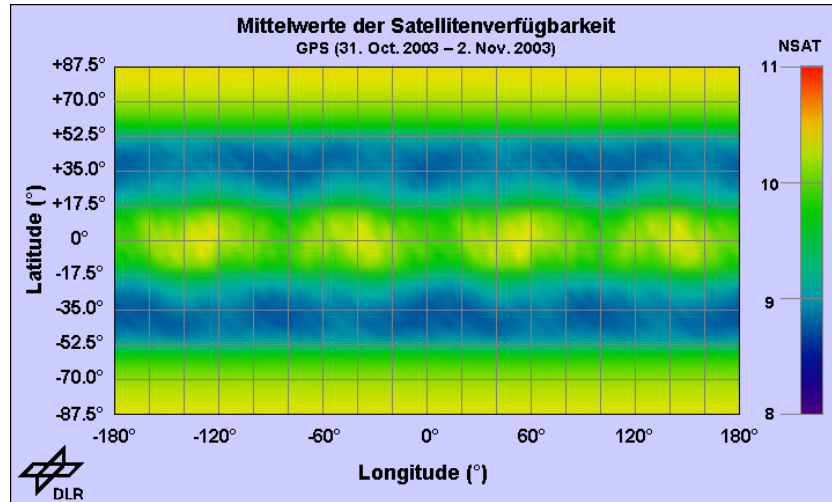
Source: Graf (DLR/TUM)





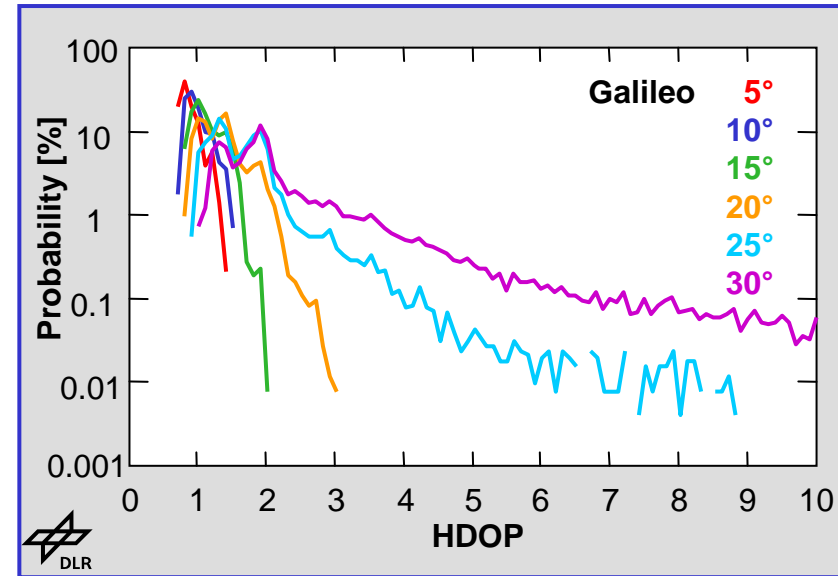
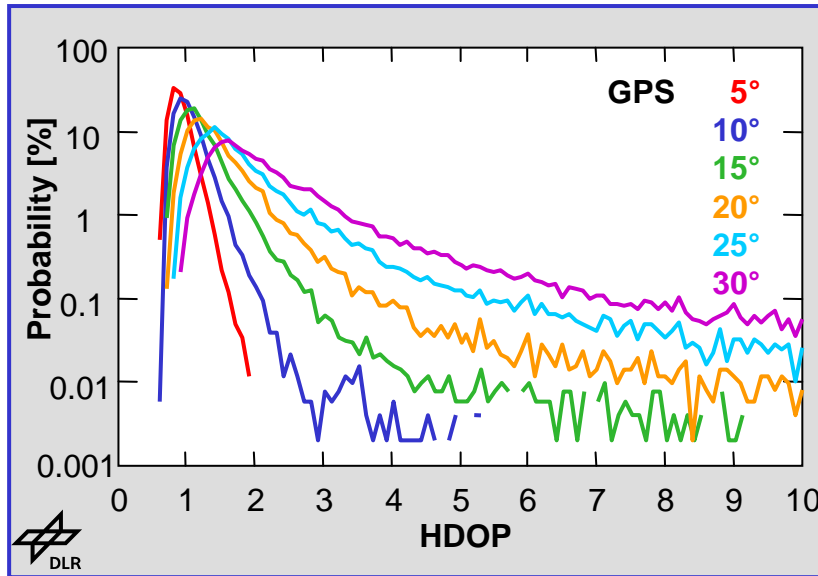


# Galileo - Konstellation



Source: NavSim (DLR)

# Galileo – Positioniergenauigkeit (HDOP)



**Prozentualer Anteil  
von Messpunkten  
mit weniger  
als 4 Satelliten**



bei ele=20°	(GPS= 0.07%,	GAL= 0.00%)
bei ele=25°	(GPS= 1.88%,	GAL= 0.00%)
bei ele=30°	(GPS= 11.46%,	GAL= 1.95%)
bei ele=35°	(GPS= 35.76%,	GAL=19.93%)
bei ele=40°	(GPS= 65.59%,	GAL=57.21%)
bei ele=45°	(GPS= 84.17%,	GAL=83.87%)

Source: NavSim (DLR)



# Mehrwert durch mehr GNSS Satelliten

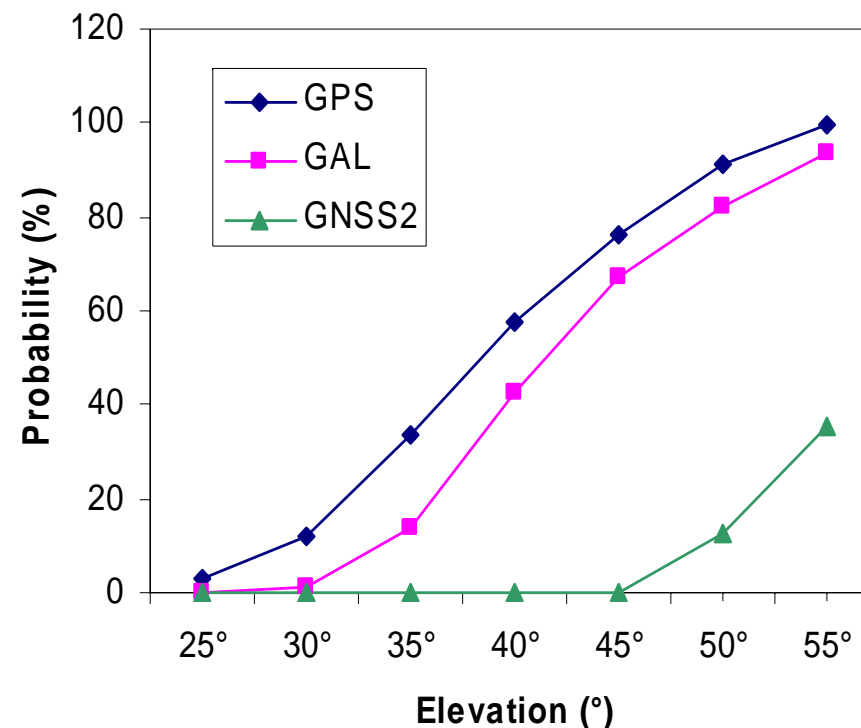
Example: Munich

**Abschattungen reduzieren die Anzahl real empfangener GNSS Signale.**

**Galileo Konstellation ermöglicht noch bei 25° Elevationsmaske die Positionierung.**

**Die gemeinsame Nutzung von GPS und Galileo reduziert das Problem des nicht ausreichenden Signalempfangs auf Elevationsmasken über 40°.**

**Non-availability (NSAT<4)**



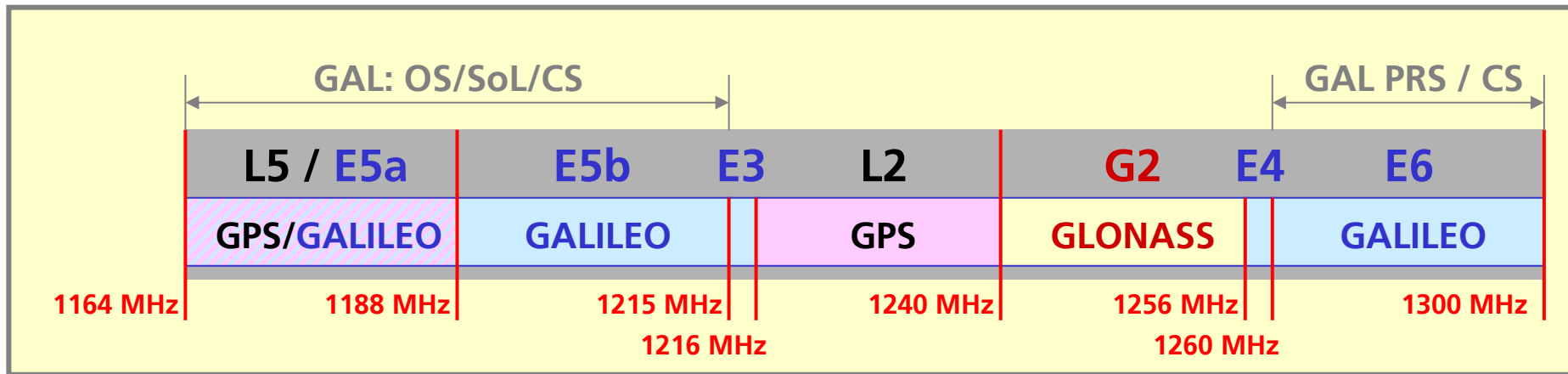
Source: NavSim (DLR)



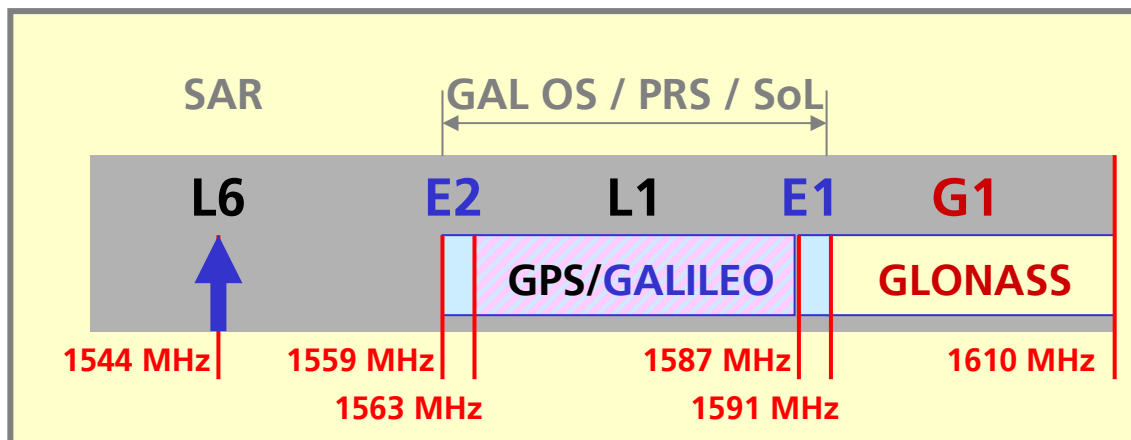


# GNSS Frequenzbänder

## Lower L-band



## Upper L-band



GPS : L1/L2 und L3  
 GPS 2: L1,L2 und L5

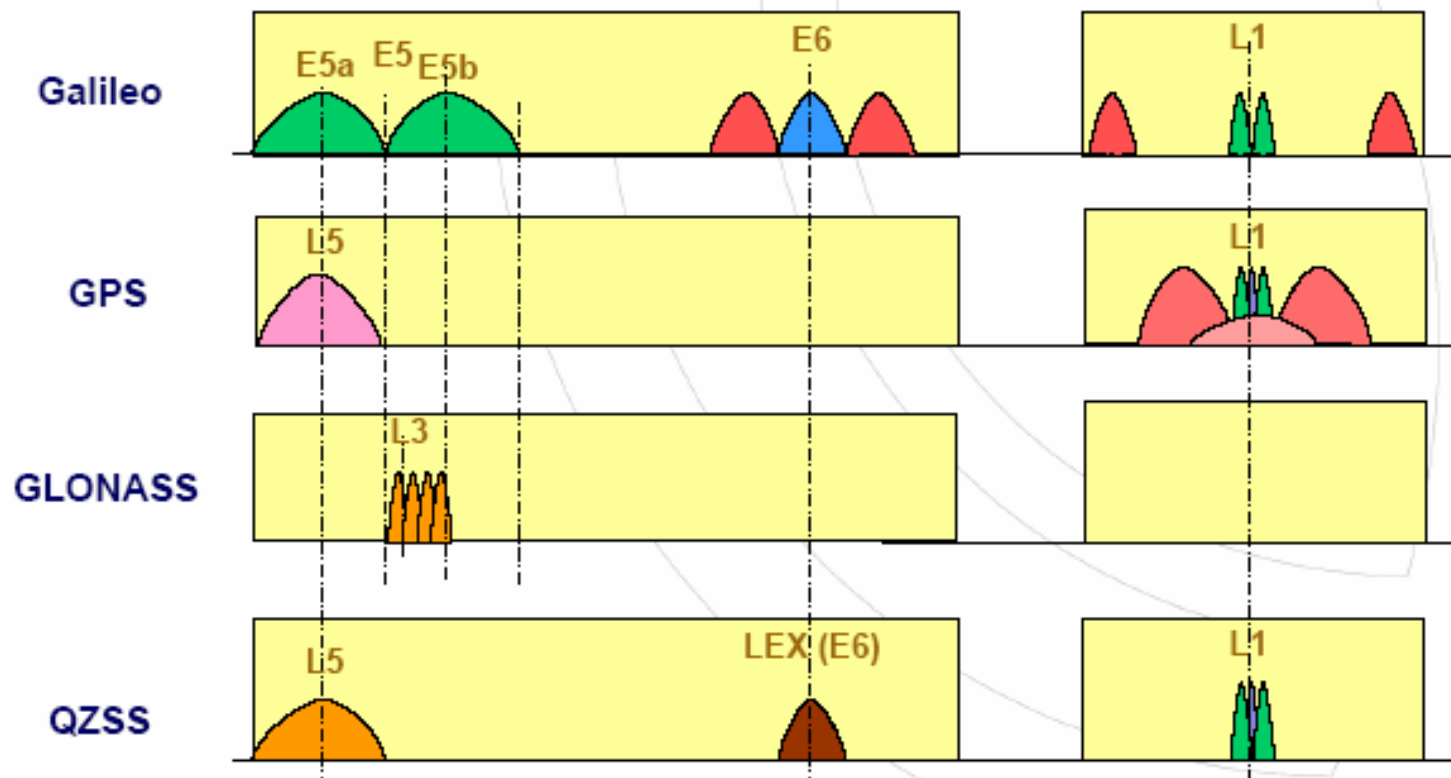
Galileo:  
 E5, E6, L1

QZSS: L1, L5, LEX(E6)



# Interoperability

Status of frequency bands Galileo has in common with other GNSS



Source: Riuz / GJU

# Galileo Signale

CASM: Coherent Adaptive  
Sub-Carrier Modulation  
BOC: Binary Offset Coding

Band	Multiplex	Bandwidth [MHz]	Component	Modulation	Power [dbm]	1. Code	2. Code	Data Rate	Service
E5	AltBOC (15,10)	90 x 1.023	E5a/I	BPSK(10)	-128	10230	20	50	OS
			E5a/Q	BPSK(10)	-128	10230	100	pilot	OS
			E5b/I	BPSK(10)	-128	10230	4	250	SoL
			E5b/Q	BPSK(10)	-128	10230	100	pilot	SoL
E6	CASM	40 x 1.023	A	BOC(10,5)	-125	classified			
			B	BPSK(5)	-128	5115	1	1000	CS
			C	BPSK(5)	-128	5115	100	pilot	CS
L1	CASM	40 x 1.023	A	BOC(15,2.5)	-125	classified			
			B	BOC(1,1)	-128	4092	1	250	OS/SoL
			C	BOC(1,1)	-128	4092	25	pilot	OS/SoL



## Galileo Services

	OS single frequency	OS dual frequency	OS improved accuracy	SoL	CS value added	CS multiple carrier	PRS
E5a <sub>IQ</sub>		●	●	●		●	
E5b <sub>IQ</sub>			●	●		●	
E6 <sub>A</sub>							●
E6 <sub>B,C</sub>					●	●	
L1 <sub>A</sub>							●
L1 <sub>B,C</sub>	●	●	●	●	●	●	



# Open Service (OS)

- Kostenfrei
- Massenmarkt
- Interoperabilität mit anderen GNSS

Time to first fix (cold start): 200 s

Time to precise fix (cold start): 100 s

Time to fix (warm start): 30 s

Time to fix (re-acquisition): 1 s

<b>Carriers</b>	<b>Single (L1)</b>	<b>Dual (L1+E5)</b>
<b>Ionospheric Corrections</b>	<b>Based on simple model</b>	<b>Based on dual processing</b>
<b>Coverage</b>	<b>Global</b>	
<b>Accuracy (95%)</b>	<b>H: 15 m V: 35 m</b>	<b>H: 4 m V: 8 m</b>
<b>Integrity</b>	<b>Alarm Limit</b>	<b>Not applicable</b>
	<b>Time-To-Alarm</b>	
	<b>Integrity Risk</b>	
<b>Availability</b>	<b>99.8 %</b>	
<b>Timing Accuracy</b>	<b>30 ns (wrt UTC/TAI)</b>	





# SoL - Service

- ICAO/IMO Regularien
- Servicegarantien
- Zertifizierbarkeit & Haftungsgarantien

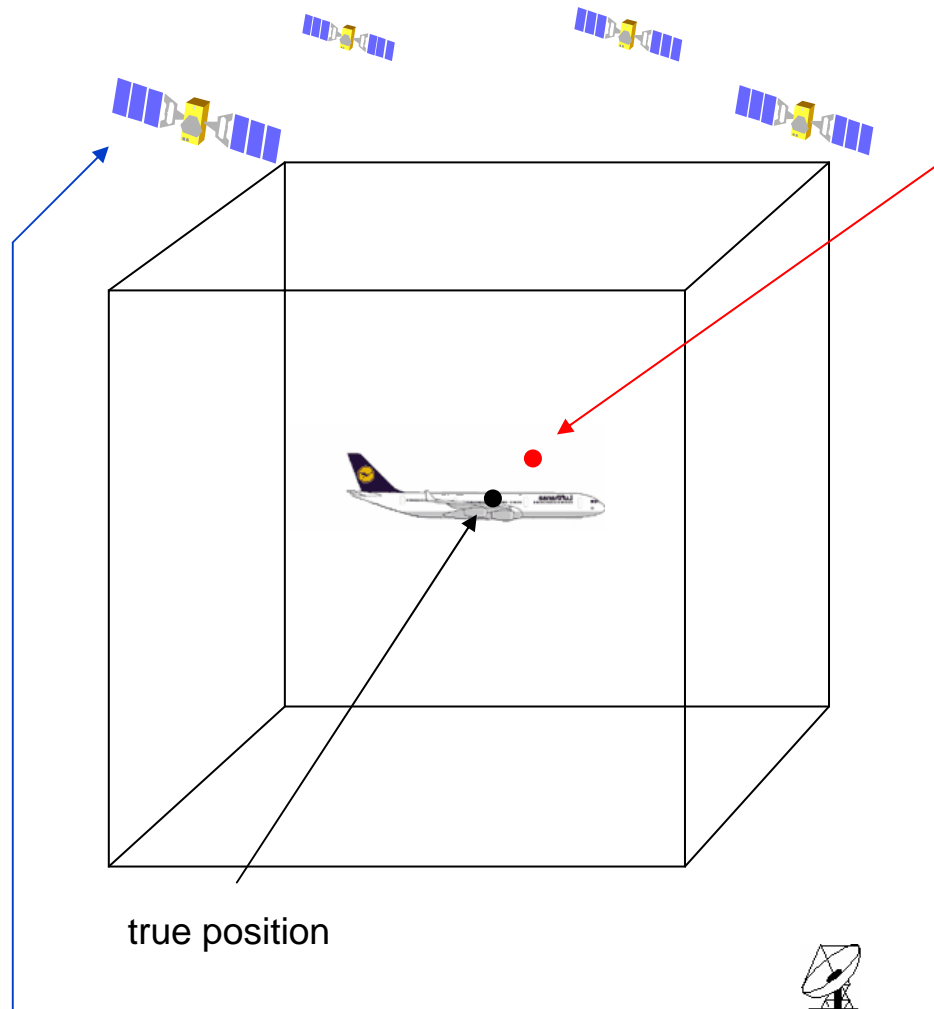
SoL =

OPEN SERVICE

+ Integrity

Carriers		Three Frequencies (L1 + E5a + E5b)	
Ionospheric Corrections		Based on dual processing	
Coverage		Global	
Time Critical Level		Y	N
Accuracy (95%)		H: 4 m V: 8 m	H: 220 m
Integrity	Alarm Limit	H: 12m / V: 20 m	H: 556 m
	Time-To-Alarm	6 sec	10 sec
	Integrity Risk	3.5e-7 / 150 s	1e-7 / h
Continuity Risk		1e-5 / 15 s	1e-4 to 1e-8 / h
Availability: Acc.		99.8 %	
Availability: Int.		99.5 %	

# Safety of Life: Concept of Integrity



measured position

## Permanently Computation of Positioning Error

- depends on satellite – receiver geometry
- determines by ranging performance

## Permanently Assessment of Positioning Error

- estimation continuously
- comparison with fixed alarm levels

## Service Operation: Provision of Alarms

Integrity risk means:

$3D \text{ Error} > 3D \text{ Alarm level}$   
without informing the user



# Public Regulated Service (PRS)

- means provision of robust and encrypted signals under EU Member States control
- will be used for applications devoted to European/national security, regulated or critical applications and activities of strategic importance
- The December `04 Transport Council:
  - has validated the PRS as one of the five Galileo services
  - has invited the Commission to develop a policy of PRS access

Carriers		Dual Frequencies (L1 + E6)
Ionospheric Corrections		Based on dual processing
Coverage		Global
Accuracy (95%)		H: 6.5 m V: 12.0 m
Integrity	Alarm Limit	H: 20 m / V: 35 m
	Time-To-Alarm	10 sec
	Integrity Risk	3.5e-7 / 150 s (tbc)
Continuity Risk		1e-5 / 15 s
Timing Accuracy		100 ns (wrt UTC/TAI)
Availability		99.8 %



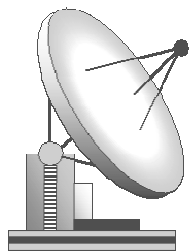
## Commercial Service (CS)

- **The Galileo Operating Company will determine and guarantee the precise levels of performance.**
  
- **Commercial Service will include:**
  - **Dissemination of data (500 bps)**
  - **Broadcasting of additional 2 signals outside from OS frequency bands**
  - **High precision navigation (dm-level)**
  - **Pilot signal for integration in positioning applications and wireless communication networks**

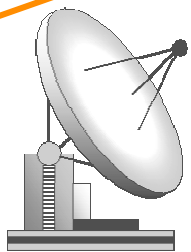
# Search and Rescue Service



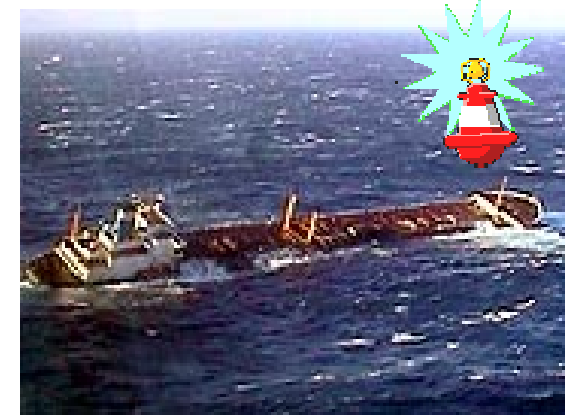
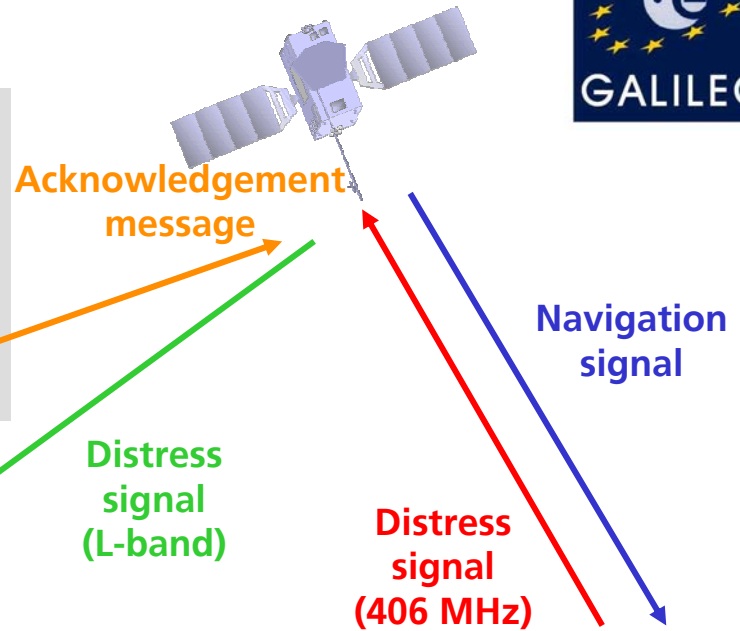
- Signale von 150 Funkbaken durch Galileo Satellit gleichzeitig weiterleitbar
- Empfangsbestätigung: 6 Messages a 100 bit pro min
- Verfügbarkeit: 99.8 %
- Kommunikation von Funkbake zur SAR Bodenstation in weniger als 10 Minuten
- BER < 1e-5



Galileo Uplink (C-band)



COSPAS SARSAT MEOLUT







## Status of Interoperability

### ● GPS and Galileo

- Adoption a common L1 signal for Galileo and GPS III: BOC(1,1)
- Interoperability of timing and geodesy standards
- Broadcasting offset of system times GPS vs. Galileo

### ● Glonass and Galileo

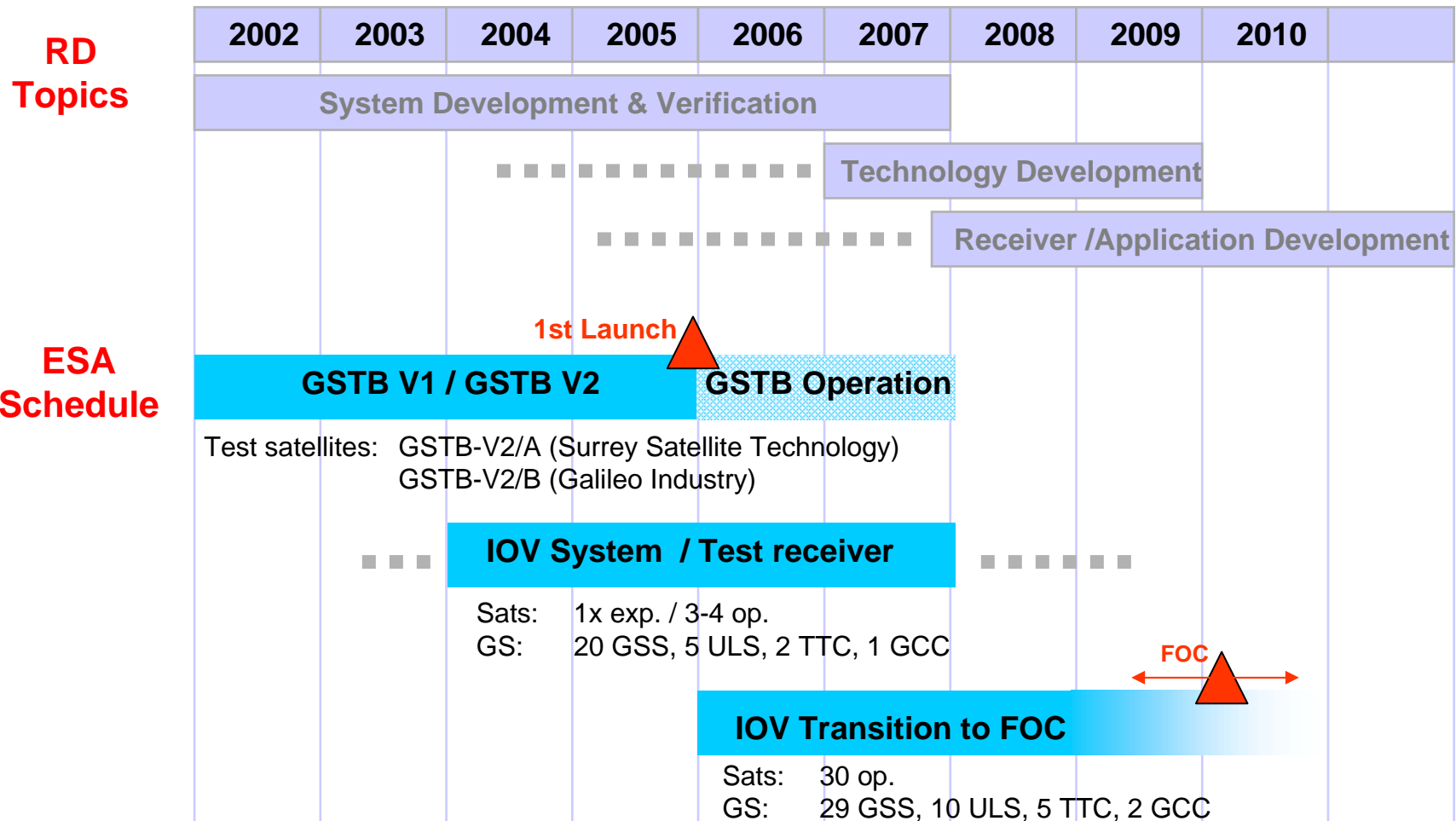
- Frequency sharing between Galileo E5b and Glonass L3 gives prospect of interoperability
- Broadcasting offset of system times Glonass-K vs. galileo is envisaged

### ● QZSS and Galileo

- Agreement that the same signal structure as Galileo E6 will be used to ensure compatibility and interoperability



# Galileo Implementierung





## Galileo – Milestone

### Start of the 1. Galileo IOV Experimentation Satellite



GIOVE -A



Launch (28. Dec. 2005)



Preparations in Baikonur

Source: ESA



# Galileo Signal Evaluation

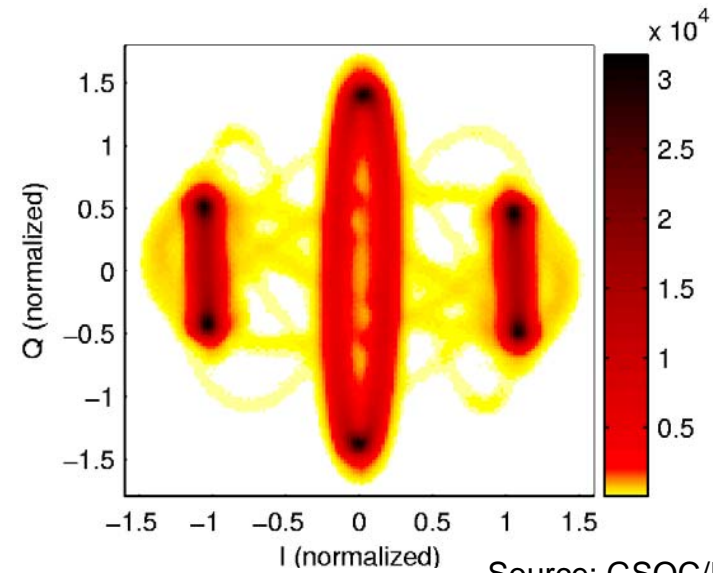
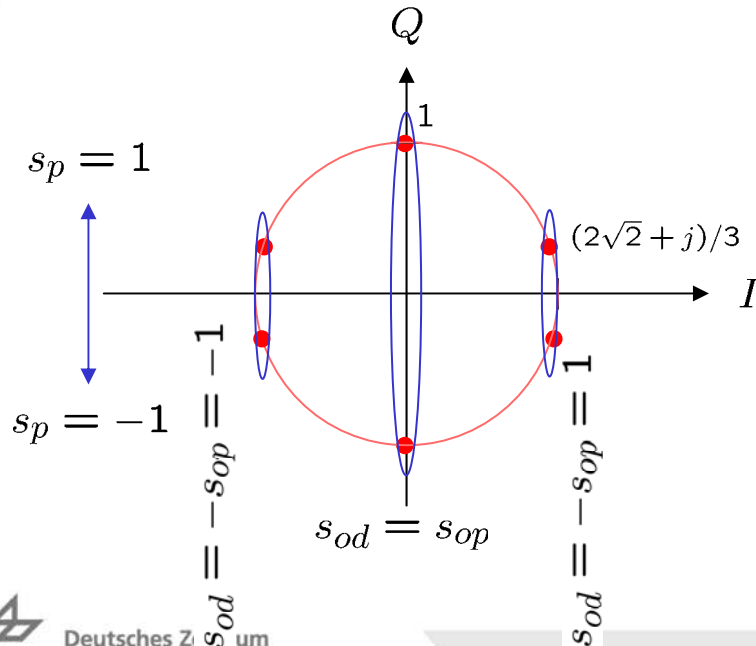
First Signals January 12<sup>th</sup>, 2006

- Measurement campaign on January 14<sup>th</sup>, 2006 on the 30 m Telescope of the DLR in Weilheim

- L1-Signal**

od = OS,data  
 op = OS,pilot  
 p = PRS

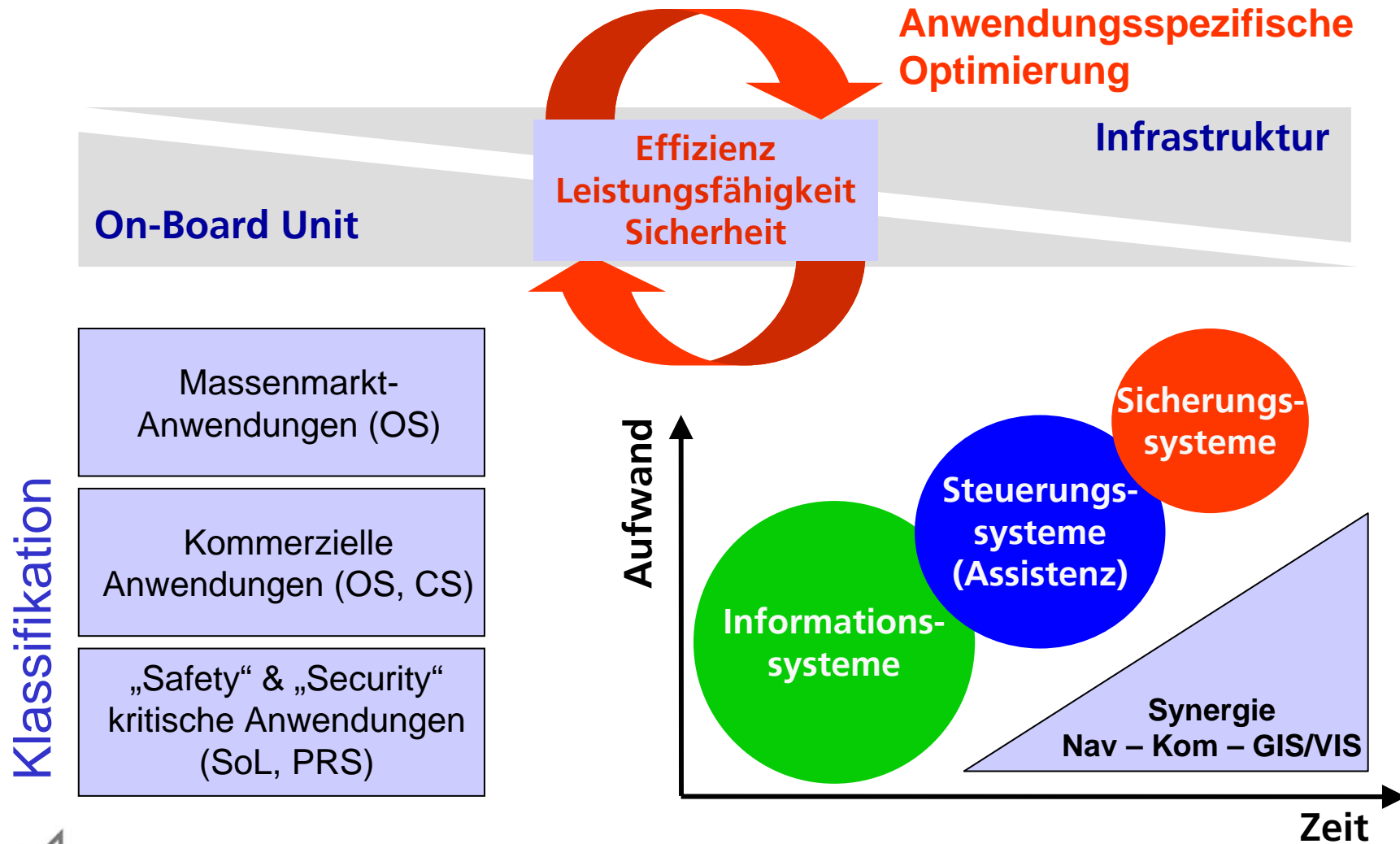
$$s_{L1}(t) = \frac{\sqrt{2}}{3} [s_{od}(t) - s_{op}(t)] \cos(\omega_{L1}t) + \frac{1}{3} [2s_p(t) + s_{od}(t)s_{op}(t)s_p(t)] \sin(\omega_{L1}t)$$



Source: GSOC/IKN (DLR)



# Galileo basierte Anwendungen

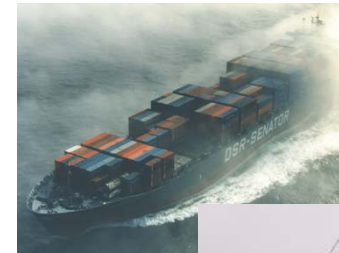






# Maritime R&D Strategy & Objectives

- >> Galileo Integration
- >> Multi-Sensor Navigation
- >> Local Augmentation



**Satellite Based Navigation**

- >> Stand alone
- >> Information aided
- >> Assisted
- >> Controlled

**Vessel Navigation Techniques**

**Innovative Solutions and Services for Efficient Vessel Guidance and Transport**

**Vessel Communication Techniques**

**Innovative Maritime Services**

- >> Service optimised
- >> Reliable
- >> Assured



- >> Information
- >> Assistance
- >> Remote control



## Mecklenburg /Vorpommern

### ● Memorandum of Understanding (21.02.2006)

- Der Freistaat Bayern, das Land Niedersachsen und das Land Mecklenburg-Vorpommern beabsichtigen, bei der Entwicklung, dem Aufbau und der Nutzung des europäischen Satellitennavigationssystems GALILEO zu kooperieren.
- **MV: Galileo Augmented Motion in Maritime Application (GAMMA)**  
Einrichtung und Betrieb einer Testumgebung für die Entwicklung maritimer Applikationen für Galileo und der Erprobung von prototypischen Anwendungen im Hafenbereich Rostock

### ● MV – 1. Progressmeeting (30.03.2006)

- Konsolidierung des Vorhabens Forschungshafen Rostock (Ministerien, FuE, KMU...)
- Konzeptentwurf bis 27.04.2006 (Phase 1) unter Federführung DLR

### ● InnoMAG – Innovative Maritime Anwendung von Galileo (29.03.2006)

- Nationale Arbeitskreisgründung unter Federführung Telematica



## Forschungshafen Rostock

**Forschungshafen  
Rostock  
=  
Maritime  
Testumgebung**



Quelle: <http://www.rostock-port.de/>



**zur Verifikation von EGNOS/Galileo/GBAS  
unter realen Bedingungen**



**zur Validierung darauf aufbauender Dienste und  
Assistenzsysteme in den Bereichen Schiffsführung,  
Verkehrsmanagement und Transportlogistik**



# Danke für Ihre Aufmerksamkeit !